

Understanding Growth through Automation: The Neoclassical Perspective

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MOTIVATION: UZAWA'S THEOREM AND AUTOMATION

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 - automation = capital autonomously completes a step of a production process
2. Follow neoclassical blueprint: Identify task technology consistent with the Kaldor facts
4. Develop a model of IT-powered automation
 - IT optimizes task load of producing task specific machines
 - IT application requires completion of tasks

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- BGP with constant LS possible; requires Pareto relative productivity of capital across tasks
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- BGP with constant LS possible; requires Pareto relative productivity of capital across tasks
 - underlying technology can be seen as nongeneric because of Pareto distribution (we show it explicitly by developing illustrative microfoundations)
- Provide a task-based microfoundation of the Cobb–Douglas production
- Identify key conditions for IT to be labor-share displacing

LITERATURE

- **Growth and automation: Acemoglu and Restrepo (2018)**
 - agnostic about the link between tasks structural change (task space static with random churning in and out of use)
 - offer different take on “horses versus humans” analogy (humans fungible, churning diffuses productivity gains across tasks)
 - different story for future: model of IT in automation vs. acceleration of trends
- Foundations of task-based theory of growth: Zeira (1998, 2006)
- Microfoundations of Cobb-Douglas pf: Jones (2005), Houthakker (1955):
 - task-based microfoundation
 - no requirement of economy-wide aggregation

Model

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- Production technology:

1. task *complexity* space: $\mathcal{Q} = \mathbb{R}_+ = [0, +\infty)$

2. *increasing* capital requirement function: $k(q)$

- labor input normalized to 1 (not an assumption)

3. measure function:

$$\mu(\mathcal{S}) := \int_{\mathcal{S}} g(q) dv,$$

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- For a given partition $\{\mathcal{Q}_k, \mathcal{Q}_l\}$ of \mathcal{Q} , producing Y units of output requires

$$K = Y \int_{\mathcal{Q}_k} k(q) d\mu \quad \text{and} \quad L = Y \int_{\mathcal{Q}_l} 1 d\mu$$

AGGREGATION

Given technology vector $T := (k, g)$, define

$$Y(T; K, L) := \sup \left\{ \hat{Y} \in \mathbb{R}_+ : \exists_{\text{m.p.}} \mathcal{Q}_l, \mathcal{Q}_k \text{ s.t. } K \geq \hat{Y} \int_{\mathcal{Q}_k} k(q) d\mu, L \geq \hat{Y} \int_{\mathcal{Q}_l} 1 d\mu \right\}$$

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ASSUMPTION

There exists a partition $\{\mathcal{Q}_k, \mathcal{Q}_l\}$ of \mathcal{Q} with $\mathcal{Q}_k \cap \mathcal{Q}_l = \emptyset$ and $\mathcal{Q}_k \cup \mathcal{Q}_l = \mathcal{Q}$ such that $\int_{\mathcal{Q}_l} 1 d\mu < \infty$ and $\int_{\mathcal{Q}_k} k(q) d\mu < \infty$, k is positive-valued function on at least part of the domain, and g has full support.

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LEMMA

There exists a unique factor utilization cutoff $q^ \geq 0$ and $\hat{Y} > 0$ such that $K = \hat{Y} \int_0^{q^*} k(q) d\mu$, $L = \hat{Y} \int_{q^*}^{\infty} d\mu$, and $Y(T; K, L) = \hat{Y}$.*

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LEMMA

Marginal products of each factor are:

$$MPK = \frac{Y}{K} \left(1 + k(q^*) \frac{L}{K} \right)^{-1} \text{ and } MPL = \frac{Y}{L} \left(1 - \frac{K}{Y} MPK \right) \quad \text{a.e.,}$$

where q^ is the factor utilization cutoff.*

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LEMMA

Suppose $T_1 = \{k_1, \mu_1\} \in \mathcal{T}$ and $T_2 = \{k_2, \mu_2\} \in \mathcal{T}$ are such that there exists a μ_1, μ_2 -measurable (and invertible) map $f : \mathcal{Q} \rightarrow \mathcal{Q}$ so that $k_1 \equiv k_2 \circ f^{-1}$ (a.e.) and $\mu_1 \equiv \mu_2 \circ f^{-1}$. Then, the aggregate production function associated to each technology is identical; that is, $Y(T_1; K, L) \equiv Y(T_2; K, L)$.

DISCRETE EXAMPLE

- Output: Hang a picture on a wall
 - ➊ move to location (coordinates) [1 labor or 2 capital]
 - ➋ take a nail from (coordinates) [1 labor or 90 capital]
 - ➌ move to location (coordinates) [1 labor or 2 capital]
 - ➍ place a nail tip against the wall (coordinates) [1 labor or 10 units of capital]
 - ➎ apply force to nail head until nailed in [1 labor or .0001 capital]
 - ➏ move to location (coordinates) [1 labor or 2 capital]
 - ➐ place picture hook on the nail [1 labor or 100 units of capital]

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Existence of BGP

GE AND GROWTH

- Given path $T_t = (k_t, \mu_t) \in \mathcal{T}$, allocation is a path of $C_t, K_t, L_t, Y_t, q_t^*$ such that

$$\max_{C_t, K_t, L_t, Y_t, q_t^*} \int_0^{\infty} e^{-\rho t} u(C_t) dt,$$

subject to

$$\begin{aligned} C_t + \dot{K}_t - \delta K_t &= Y_t, \\ L_t &= \bar{L}, \end{aligned}$$

where q_t^* satisfies

$$K_t = Y_t \int_0^{q_t^*} k_t(q) d\mu_t, \quad L_t = Y_t \int_{q_t^*}^{\infty} d\mu_t.$$

DEFINITION OF BALANCED GROWTH PATH

DEFINITION

A balanced growth path with automation and constant factor shares (BGP) comprises an allocation sequence: $Y_t = Y_0 e^{\gamma_Y t}$, $C_t = C_0 e^{\gamma_C t}$, $K_t = K_0 e^{\gamma_K t}$, $q_t^* = q_0^* e^{\gamma_{q^*} t}$ and a technology sequence $T_t = \{k_t(q) = k_0(q) e^{\gamma_k t}, g_t(q) = g_0(q) e^{\gamma_g t}\} \in \mathcal{T}$, such that $\gamma_Y > 0, \gamma_{q^*} > 0$ and $\alpha \equiv \frac{K_t}{Y_t} MPK_t$ is constant, where $\gamma_k, \gamma_g, Y_0 > 0, C_0 > 0, K_0 > 0, q_0^* > 0$ are scalars.

- We use the standard approach of assuming “stable shape” conditions on g and k
- Not an assumption: Justified by random task churning. (Will come back to this.)

BALANCED GROWTH PATH EXISTENCE

PROPOSITION

If $\gamma_k < 0$ and $\gamma_g - \alpha\gamma_k > 0$, BGP exists and features:

① Technology

$$T_0 = \left\{ k_0(q) = k_0 q^\theta, g_0(q) = g_0 q^{-\zeta-1} \right\},$$

where $\zeta := \frac{\gamma_Y + \gamma_g}{\gamma_{q^*}}$, $\theta := \frac{\gamma_Y - \gamma_k}{\gamma_{q^*}}$,

② Growth rates: $\gamma := \gamma_Y = \gamma_C = \gamma_g - \alpha\gamma_k$.

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COROLLARY

The aggregate production function along the BGP is Cobb–Douglas; that is, output Y_t and marginal products MPK_t and MPL_t are consistent with those implied by

$$Y_t(K, L) = A_t (Z_t K)^\alpha L^{1-\alpha}$$

where $\alpha = \frac{\zeta}{\theta}$ and $A_t > 0$, $Z_t > 0$ are scalars that grow at a constant rate.

PROOF OUTLINE

1. Standard: Y, C, K grow at same rate γ
2. Given constant growth q^* , $k(q)$ must be CES because

$$\alpha = \frac{K}{Y} MPK = \left(1 + k(q^*) \frac{L}{K} \right)^{-1}$$

3. Given output growth, labor input must decline at rate γ because

$$\bar{L} = Y \int_{q^*}^{\infty} 1g(q)dv$$

Nongeneric nature of BGP task technology

NONGENERIC NATURE OF CD TASK TECHNOLOGY

- Nongeneric to the extent that Pareto distributed capital requirements is, since

$$Pr(\mathbf{k} \geq k | \mathbf{k} \geq k_0) = Pr(q \geq k^\alpha | q \geq k_0^\alpha) = \left(\frac{k}{k_0}\right)^{-\alpha}$$

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- Implies Pareto distributed k :

$$Pr(k_0 e^{\gamma\tau} \geq k) = Pr\left(\tau \geq \gamma^{-1} \log \frac{k}{k_0}\right) = e^{-\frac{\mu}{\gamma} \log \frac{k}{k_0}} = \left(\frac{k}{k_0}\right)^{-\frac{\mu}{\gamma}}$$

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- Churning in and out of use adds *random growth* that also leads to Pareto pdf

COMMENT: ISSUE WITH INFINITE MEASURE

- In baseline CD model measure of tasks is infinite, i.e., $\mu(\mathcal{Q}) = \infty$
- Can work instead with the following truncation technology (for q_0 small enough):

$$T = \left(k(q) = Z^{-1} (q + q_0)^{\frac{1}{\alpha}} \frac{1 - \alpha}{\alpha}, g(q) = A^{-1} (q + q_0)^{-2} \right)$$

Effect of technical change on the labor share

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FRAMEWORK: REPRESENTATIVE COMPETITIVE FIRM

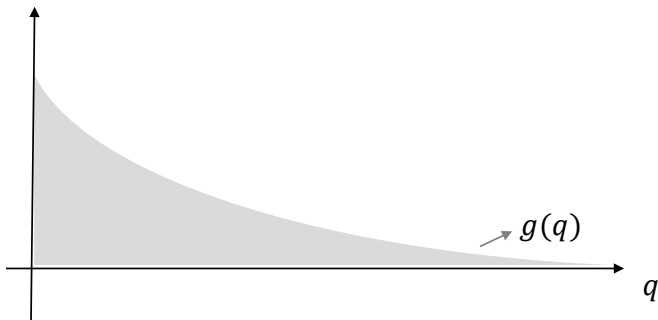
- Define prices: w (wage), r (user cost of capital), P (output)
- Profit maximization implies $P = c(w, r)$
- Cost minimization implies
 - firm chooses a cutoff q^* to minimize

$$c(w, r) := wL + rK$$

where

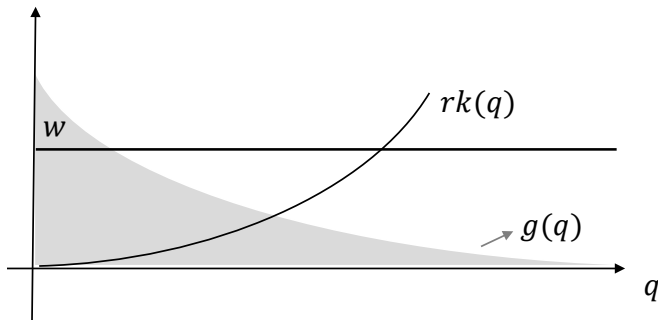
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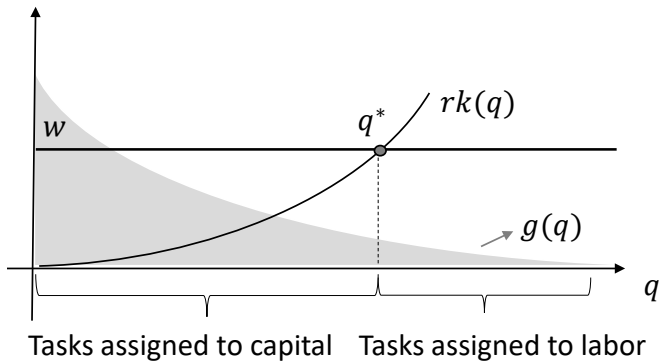


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FRAMEWORK: REPRESENTATIVE COMPETITIVE FIRM



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FRAMEWORK: PERTURBATION OF TECHNOLOGY

- Define a perturbation of technology $T = (k, g)$:

$$T_\varepsilon := (k, g) + \varepsilon(\Delta k, \Delta g)$$

- Evaluate the marginal effect ε at $\varepsilon = 0$

FRAMEWORK: LABOR SHARE DECOMPOSITION

- Labor share:

$$LS_{\varepsilon} := \frac{w}{P_{\varepsilon}} \frac{L}{Y_{\varepsilon}} (q_{\varepsilon}^*),$$

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$$LS_{\varepsilon} := \frac{w}{P_{\varepsilon}} \frac{L}{Y_{\varepsilon}} (q_{\varepsilon}^*),$$

- Decomposition:

$$\frac{d \log LS_{\varepsilon}}{d\varepsilon} \Big|_{\varepsilon=0} = \underbrace{\frac{d \log \frac{L}{Y_{\varepsilon}} (q_{\varepsilon}^*)}{d\varepsilon} \Big|_{\varepsilon=0}}_{\text{displacement effect DE}} + \underbrace{-\frac{d \log P_{\varepsilon}}{d\varepsilon} \Big|_{\varepsilon=0}}_{\text{productivity effect PE}}$$

where

$$\begin{aligned} PE = & \underbrace{-\frac{1}{P} \left(w \frac{d \frac{L}{Y} (q^*)}{dq^*} + r \frac{d \frac{K}{Y} (q^*)}{dq^*} \right) \frac{dq_{\varepsilon}^*}{d\varepsilon} \Big|_{\varepsilon=0} - \frac{1}{P} \int_0^{q^*} \frac{\Delta g(q)}{g(q)} k(q) d\mu}_{\text{automation}} \\ & + \underbrace{\frac{1}{P} \int_0^{q^*} r \Delta k(q) d\mu}_{\text{direct technical change effect}}, \end{aligned}$$

FRAMEWORK: LABOR SHARE DECOMPOSITION

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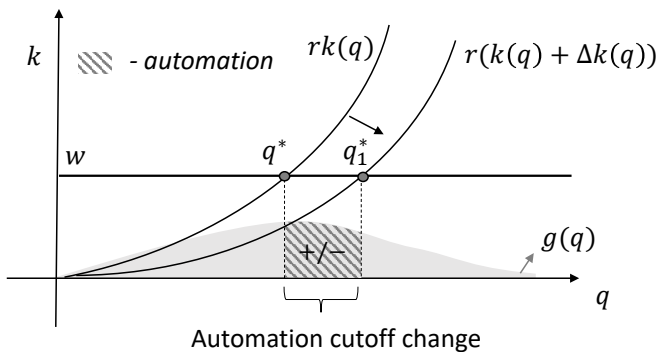
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CASE 1: Δk PERTURBATION



EFFECT OF Δk PERTURBATION

PROPOSITION

Δk -biased capital-augmenting technical progress changes the labor share by

$$\frac{d \log LS_\varepsilon}{d\varepsilon} \Big|_{\varepsilon=0} = \underbrace{\frac{d \log \frac{L}{Y}_\varepsilon (q_\varepsilon^*)}{d\varepsilon} \Big|_{\varepsilon=0}}_{\text{displacement effect } DE} + \underbrace{-\frac{d \log P_\varepsilon}{d\varepsilon} \Big|_{\varepsilon=0}}_{\text{productivity effect } PE} \quad (\text{a.e.})$$

where

$$DE = -h(q^*) \frac{\Delta k(q^*)}{k'(q^*)}$$

$$PE = \frac{1}{P} \int_0^{q^*} r \Delta k(q) d\mu = h(q^*) LS \frac{\int_0^{q^*} \Delta k(q) g(q) dv}{k(q^*) g(q^*)}$$

and where q^* is the initial automation cutoff such that at that cutoff point $k(q)$ is strictly increasing and differentiable, $S(q^*) = \int_{q^*}^\infty d\mu$ is the survival function, and

$h(q) := -\frac{dS(q)}{dq} = \frac{g(q)}{S(q)}$ is the hazard rate.

EFFECT OF Δk PERTURBATION

Consider marginal progress: $\Delta k(q^*) > 0$, otherwise $\Delta k(q) = 0$.

PROPOSITION

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EFFECT OF Δk PERTURBATION

Consider fully diffused progress: $\Delta k(q) = k(q)$.

PROPOSITION

Δk -biased capital-augmenting technical progress changes the labor share by

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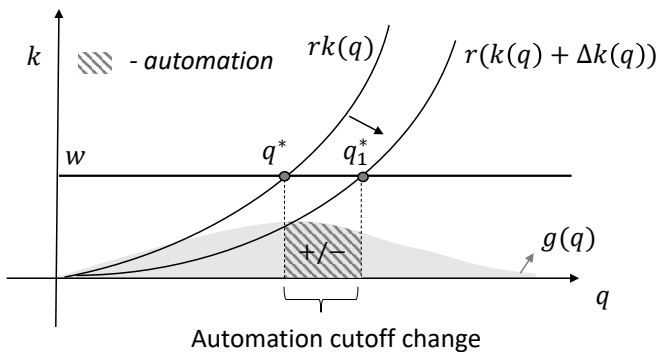
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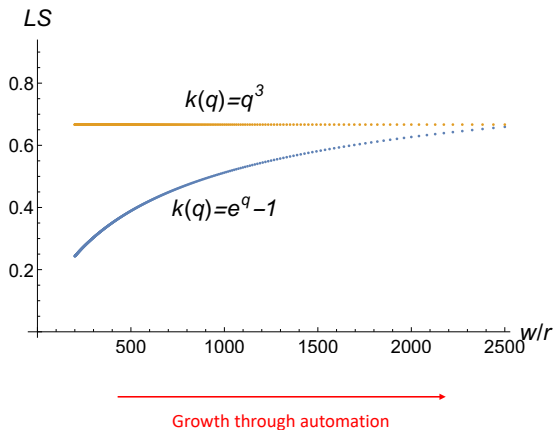
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FULLY DIFFUSED Δk PERTURBATION

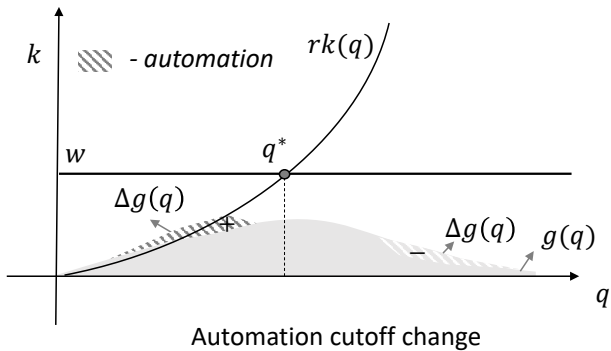


NUMERICAL EXAMPLE

$$T = (k(q) = \dots, g(q) = (q + .1)^{-2})$$

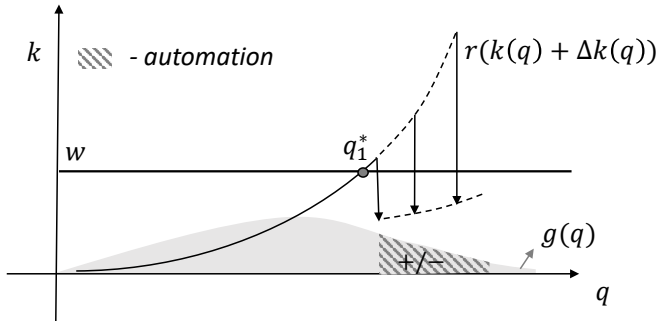


CASE 2: Δg PERTURBATION



CASE 2: Δg PERTURBATION

Equivalent to scattered jump in Δk under the automation cutoff:



EFFECT OF Δg PERTURBATION

Intuition: Decline in P augments income of both factors in proportion to their share.

PROPOSITION

Δg -biased complexity reducing technical progress changes the labor share by

$$\frac{d \log LS_\varepsilon}{d\varepsilon} \Big|_{\varepsilon=0} = \underbrace{\frac{d \log \frac{L}{Y}_\varepsilon(q_\varepsilon^*)}{d\varepsilon} \Big|_{\varepsilon=0}}_{\text{displacement effect DE}} + \underbrace{-\frac{d \log P_\varepsilon}{d\varepsilon} \Big|_{\varepsilon=0}}_{\text{productivity effect PE}} \quad (\text{a.e.})$$

where

$$DE = \frac{d \log S(q_\varepsilon^*)}{d\varepsilon} \Big|_{\varepsilon=0} = -h(q^*) \frac{\int_0^{q^*} \frac{w}{r} \frac{\Delta g(q)}{g(q)} d\mu}{g(q^*) k(q^*)}$$

$$PE = \frac{1}{P} \int_0^{q^*} \frac{\Delta g(q)}{g(q)} (w - rk(q)) d\mu = h(q^*) LS \left(\frac{\int_0^{q^*} \frac{\Delta g(q)}{g(q)} \left(\frac{w}{r} - k(q) \right) d\mu}{g(q^*) k(q^*)} \right)$$

and where q^* is the initial automation cutoff such that at that cutoff point $k(q)$ is strictly increasing and differentiable, $S(q^*) = \int_{q^*}^\infty d\mu$ is the survival function, and

$h(q) := -\frac{dS(q)}{dq} = \frac{g(q)}{S(q)}$ is the hazard rate.

EFFECT OF Δg PERTURBATION

Intuition: Decline in P augments income of both factors in proportion to their share.

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where

$$DE + PE = -\frac{h(q^*)}{g(q^*)k(q^*)} \left(\int_0^{q^*} \frac{\Delta g(q)}{g(q)} \left(\frac{w}{r} (1 - LS) + k(q) LS \right) d\mu \right) < 0$$

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KEY LESSONS

- Technical progress is generally labor-share displacing if
 - Δk -change is “complexity biased” (maximizes marginal effect)
 - small for k low
 - high for k high
 - or involves Δg progress (software/digitization)

Model of IT in automation

EXTENDED SETUP

- Capital \Rightarrow machines that are task q specific

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$$Pk(q) := \min_{\{\mathcal{Q}_k, \mathcal{Q}_l\}} \left\{ r \int_{\hat{q} \in \mathcal{Q}_k} k(\hat{q}) \tilde{g}_q(\hat{q}) dv + w \int_{\hat{q} \in \mathcal{Q}_l} \tilde{g}_q(\hat{q}) dv \right\}.$$

where $\mathcal{Q}_k, \mathcal{Q}_l$ is a measurable partition of \mathcal{Q} and $\tilde{g}_q(\hat{q})$ is density of required tasks

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- Technology is $\tilde{T}_q = \{\tilde{g}_q\}$, and in goods producing sector $T = \{g\}$

ASSUMPTION

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$\tilde{g}_q(\hat{q}) = \lambda(q) g(\hat{q})$, where $g(\hat{q}) = A^{-1} \hat{q}^{-2}$ and $\lambda(q) = Z^{-1} q^{\frac{1}{\alpha}}$.

PROPOSITION

The production function in the capital q -producing sector is Cobb–Douglas of the form:

$$Y_q(K, L) = Zq^{-\frac{1}{\alpha}} A \left(Z \left(\frac{c(w, r)}{P} \right)^{-1} \frac{\alpha}{1 - \alpha} K \right)^{\alpha} L^{1-\alpha},$$

and the endogenous capital requirement function is

$$k(q) = \underbrace{Z^{-1} q^{\frac{1}{\alpha}}}_{=\lambda(q)} \frac{c(w, r)}{P},$$

where $c(w, r)$ is the unit cost of production in the capital producing sector associated with the base technology $T = \{g\}$. If, in addition, $g(q) = A^{-1}q^{-2}$, the production function in the goods sector is also Cobb–Douglas and takes the form:

$$Y(K, L) = A \left(Z \left(\frac{c(w, r)}{P} \right)^{-1} \frac{\alpha}{1 - \alpha} K \right)^{\alpha} L^{1-\alpha}.$$

MODEL OF IT IN AUTOMATION

DEFINITION

A breakthrough IT automation technology comprises:

- ① *A task technology $T^{IT} = \{g^{IT}\}$.*
- ② *An associated strictly decreasing compression function $\kappa : \mathbb{R}_+ \rightarrow \mathbb{R}_+$, such that T^{IT} used $n \geq 0$ times “compresses” the task load in the production of machines of type $q \in \mathcal{Q}$ by factor $\kappa(n)$, implying transformed task density is $\tilde{g}_{q,n}(\hat{q}) = \kappa(n) \lambda(q) g(\hat{q})$. (Units sufficiently small to justify the use of $n \in \mathbb{R}_+$.)*

ASSUMPTION

$\kappa(n) = \kappa_0 \beta^{-1} n^{-\beta}$, where $0 < \beta < \alpha^{-1} - 1$ and $\kappa_0 > 0$ are scalars.

Implies a single application of IT reduces task load by β percent.

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Effect of IT on the labor-share

EFFECT OF IT ON CAPITAL REQUIREMENT FUNCTION

- Application of IT transforms capital requirement $k_{old}(q) = q^{\frac{1}{\alpha}}$ to

$$k_{new}(q) = \min \left\{ q^{\frac{1}{\alpha}}, \min_{n \geq 0} \kappa(n) q^{\frac{1}{\alpha}} + bn \right\},$$

where $b > 0$ is cost of applying IT once

EFFECT OF IT ON CAPITAL REQUIREMENT FUNCTION

- Application of IT transforms capital requirement $k_{old}(q) = q^{\frac{1}{\alpha}}$ to

$$k_{new}(q) = \begin{cases} q^{\frac{1}{\alpha}} & q \leq q_{\min} \\ Cq^{\frac{1}{\alpha} \frac{1}{1+\beta}} & q \geq q_{\min} \end{cases},$$

where $C > 0$ ensures continuity

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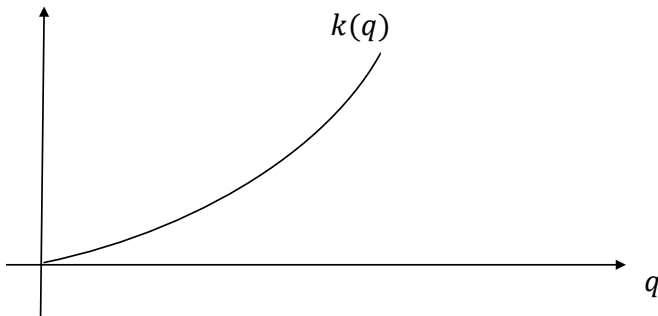
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\Rightarrow After dropping constants implies: $k_{old}(q) \propto q^{\frac{1}{\alpha}} \rightarrow k_{new}(q) \propto q^{\frac{1}{\alpha} \frac{1}{1+\beta}}$

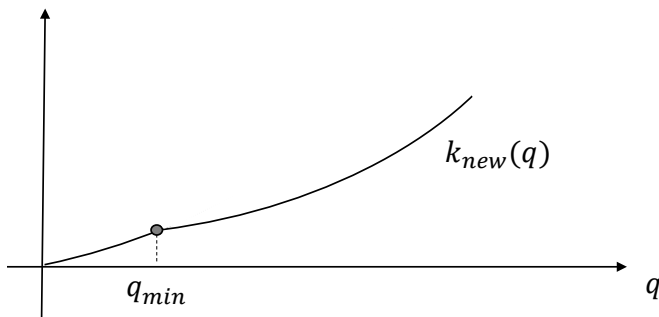
EFFECT OF IT ON CAPITAL REQUIREMENT FUNCTION

- Optimization implies breakthrough technology applied iff $q \geq q_{\min} > 0$:



EFFECT OF IT ON CAPITAL REQUIREMENT FUNCTION

- Optimization implies breakthrough technology applied iff $q \geq q_{\min} > 0$:



EFFECT OF AUTOMATION BREAKTHROUGHS ON PRODUCTION

PROPOSITION

The post-breakthrough labor share converges to $LS_{new} = LS_{old} - \alpha\beta$ as the economy further automates so that $q_{min}/q^ \rightarrow 0$.*

DISCUSSION

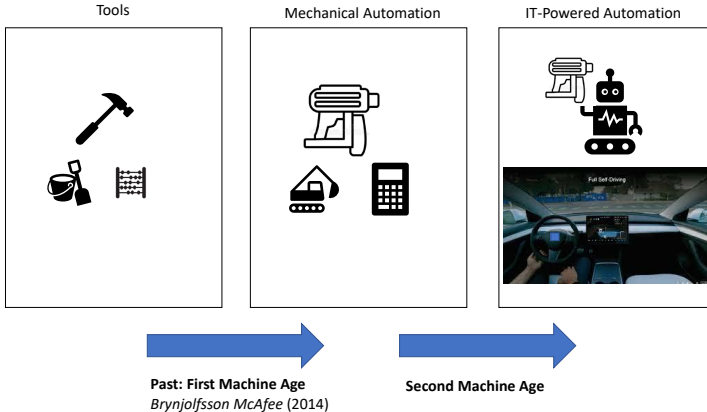
- Key properties that make IT labor-share displacing are
 - universality - applies to most tasks
 - task compression - reduces task load in proportion to the initial load
 - scalability - can be scaled up when payoff is bigger
- Interpretable under Brynjolfsson and McAfee's (2014) view of the second machine age

DISCUSSION

Brynjolfsson McAfee (2014): automation requires *power* and *cognition*

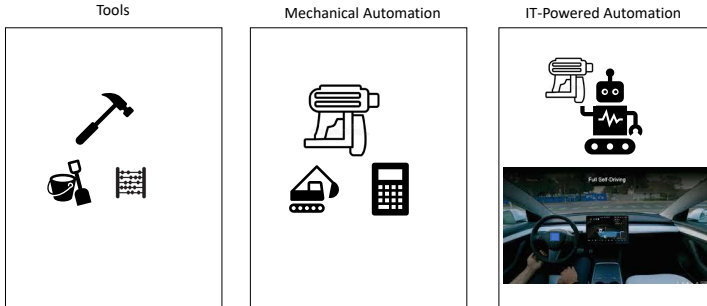
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Brynjolfsson McAfee (2014): automation requires *power* and *cognition*



Past: First Machine Age
Brynjolfsson McAfee (2014)

Second Machine Age

$$\min \left\{ \text{power}_i, \left(\text{cognition}_i^{\frac{1}{\rho_i}} + \text{mechanism}_i^{\frac{1}{\rho_i}} \right)^{\rho_i} \right\} \geq 1$$

CONCLUSIONS

- Developed theory of automation consistent with the past growth experiences
- Showed the obtained task technology can be thought of as nongeneric
- Provided a mechanism explaining labor-share displacing effect of IT-powered automation

APPENDIX

AUTOMATION A LEADING HYPOTHESIS FOR LABOR SHARE DECLINES

- **Automation**

Acemoglu and Restrepo (2018, 2019, 2020)

Restrepo and Hubmer (2022)

Graetz and Michaels (2018)

Autor and Salomons (2018)

- **Market power**

Autor et al. (2017)

- **Outsourcing**

Gianonni and Mertens (2020)

- **Other**

Basket composition: Humbner (2020)

Taxes: Kaymak and Schott (2018)

Measurement Gutierrez and Piton (2020), Koh et al. (2020)

